A Critique on Average-Case Noise Analysis in RLWE-Based Homomorphic Encryption

Mingyu Gao Hongren Zheng

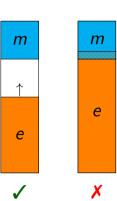
WAHC' 25

Recap: RLWE-based Homomorphic Encryption

Secret key
$$s$$
 Message Δm Noise e $\left(as + \Delta m + e, a\right)$

- Polynomial ring $\mathcal{R} = \mathbb{Z}[X]/(X^N + 1)$
- \blacksquare a, s, m, e are polynomials
- Poly multiplication is coeff convolution

$$a\cdot b=\sum_{i=0}^{2N-1}\left(\sum_{j+k=i}a_jb_k
ight)X^i\pmod{X^N+1}$$



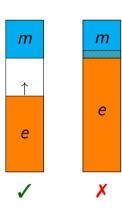
Recap: RLWE-based Homomorphic Encryption

Secret key
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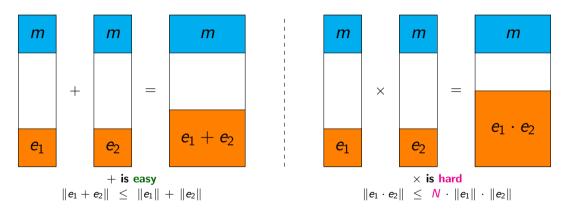
- Message in high bits
- Noise grows after HE operations
- Noise should never overflow

correctness
$$\leftarrow \xrightarrow{tradeoff}$$
 efficiency $\downarrow \downarrow$

Noise Analysis



Worst-Case Noise Analysis



- N is worst-case expansion factor, very conservative and undesired
- Empirically, growth should be $C\sqrt{N}$

Average-Case Noise Analysis: Variance-Based

$$e \longrightarrow \mathsf{Var}(e)$$

Gaussian Heuristic ($m{x}$)
 $\|e\| = 6\sigma$

Previous Workflow

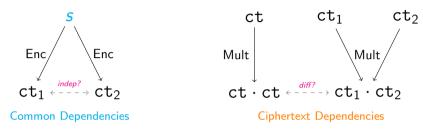
- [CCH⁺24]: Noises follow *Gaussian* distribution
 - Estimate the variance Var(e) after each step
 - Finally induce the *Gaussian* bound ||e||
- Contribution 1: Invalidate the Gaussian Heuristic
 - Noises are not Gaussian after deep multiplications

$$e \longrightarrow \mathsf{Var}(e)$$
Heavier tail
$$\mathsf{Larger} \ \|e\|$$

Our Observation

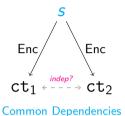
$$\mathsf{Var}(e_1 + e_2) = \mathsf{Var}(e_1) + \mathsf{Var}(e_2)$$
 $\mathsf{Var}(e_1 \cdot e_2) = \mathcal{N} \cdot \mathsf{Var}(e_1) \cdot \mathsf{Var}(e_2)$
 $\downarrow \mathcal{X}$
 $\|e_1 \cdot e_2\| = \sqrt{\mathcal{N}} \cdot \|e_1\| \cdot \|e_2\|$

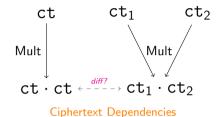
Dependencies



- Contribution 2: Study *dependencies* in noise analysis
- Previously, use Independence Heuristic because dependencies are hard
- Two types of dependencies
 - Common dependencies: All ct share secret key s
 - Ciphertext dependencies: ct · ct v.s. ct₁ · ct₂

Dependencies





- Common Dependencies
- Contribution 2: Study *dependencies* in noise analysis
- Previously, use Independence Heuristic because dependencies are hard
- Two types of dependencies
 - Common dependencies: All ct share secret key s
 - Ciphertext dependencies: $ct \cdot ct \ v.s. \ ct_1 \cdot ct_2$
- Contribution 3: Find flaws in OpenFHE empirical formula
 - Root cause: Gaussian Heuristic + Independence Heuristic
 - Special cases will violate both

Section 1

Technical Details

Noise in BFV

- Polynomial ring $\mathcal{R} = \mathbb{Z}[X]/(X^N + 1)$, N power of 2
- Noise $e \leftarrow \mathcal{N}(0, \sigma^2)$ with Gaussian coefficients
- Secret key $s \leftarrow \{-1,0,1\}$ with uniform ternary coefficients

$$pk = (-as + e_{pk}, a)$$

$$ct = u_{ct} \cdot pk + (\Delta m + e_{ct}, e'_{ct})$$

$$ct(s) = \Delta m + \underbrace{e_{ct} + u_{ct} \cdot e_{pk} + e'_{ct} \cdot s}_{\text{Noise } v}$$

- lacktriangle Common dependencies: secret key s and noise in public key $e_{
 m pk}$
- Ciphertext dependencies: ciphertext specific u_{ct} and e_{ct}

BFV ct in $\mathcal{R}/Q\mathcal{R}$. Multiplication happens in \mathcal{R} . $\mathtt{ct}_1(s) = \Delta m_1 + v_1 + h_1 Q$ $h_1 Q \approx c_1 \boxed{s}$ $h_1 \approx \mu_{\mathtt{ct}_1} \boxed{s}$ $(\mathtt{ct}_1 \otimes \mathtt{ct}_2)(s) = v_1 h_2 + v_2 h_1 + \cdots$ $= \boxed{s^2} \cdot (\mu_{\mathtt{ct}_2} e_{\mathtt{ct}_1}) + \cdots$

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$$(\mathsf{ct}_1 \otimes \mathsf{ct}_2)(s) = v_1 h_2 + v_2 h_1 + \cdots$$

$$= \boxed{s^2} \cdot (\mu_{\mathsf{ct}_2} e_{\mathsf{ct}_1}) + \cdots$$

$$\left(\bigotimes^k_i \mathsf{ct}_i \right)(s) = \boxed{s^k} \cdot \left(\prod \mu_{\mathsf{ct}_i} e_{\mathsf{ct}_j} \right) + \cdots$$

Assume relinearize after each multiplication but introduces negligible noise

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$$(\operatorname{ct}_1 \otimes \operatorname{ct}_2)(s) = v_1 h_2 + v_2 h_1 + \cdots$$

$$= \boxed{s^2} \cdot (\mu_{\mathtt{ct}_2} e_{\mathtt{ct}_1}) + \cdots$$

$$(\bigotimes_i^k \operatorname{ct}_i^k)(s) = \boxed{s^k} \cdot \left(\prod_i^k \mu_{\mathtt{ct}_i} e_{\mathtt{ct}_i}\right) + \cdots$$

$$\operatorname{ct}^k(s) = \boxed{s^k \mu_{\mathtt{ct}}^{k-1}} \cdot e_{\mathtt{ct}} + \cdots$$

Assume relinearize after each multiplication but introduces negligible noise

k-way multiplication contains high degree terms

- *s^k* in noise *generally*
- μ_{ct}^{k-1} in noise in specific circuit

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- μ_{ct}^{k-1} in noise in specific circuit
- Lazy relinearize makes degree higher

BFV ct in \mathcal{R}/\mathcal{QR} . Multiplication happens in \mathcal{R} .

$$ext{ct}_1(s) = \Delta m_1 + v_1 + h_1 Q$$
 $h_1 Q pprox c_1 s$
 $h_1 pprox \mu_{\mathtt{ct}_1} s$
 $(\mathtt{ct}_1 \otimes \mathtt{ct}_2)(s) = v_1 h_2 + v_2 h_1 + \cdots$
 $= s^2 \cdot (\mu_{\mathtt{ct}_2} e_{\mathtt{ct}_1}) + \cdots$
 $(t^k(s)) = s^k \cdot (\prod \mu_{\mathtt{ct}_i} e_{\mathtt{ct}_j}) + \cdots$

Assume relinearize after each multiplication but introduces negligible noise

k-way multiplication contains high degree terms

- s^k in noise generally
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Need to study distribution of

- Product of Gaussians: $\prod f_i$
- Power of one Gaussian: f^k
- Mixed Product of Gaussians: $\prod f_i^{k_i}$

Are they Gaussian?

 \Rightarrow Study the Kurtosis!

Kurtosis/Bound of Gaussian

Definition (Kurtosis)

The **Kurtosis** of a zero-mean random variable X is defined as

$$\mathsf{Kurt}(X) = \frac{\mathbb{E}[X^4]}{(\mathbb{E}[X^2])^2} = \frac{\mathbb{E}[X^4]}{\mathsf{Var}(X)^2}$$

- Kurtosis measures tailedness [Wes14]
- Gaussian has *constant* Kurt = 3

$$\mathsf{Kurt}(\mathcal{N}(0,\sigma^2)) = \frac{3\sigma^4}{(\sigma^2)^2} = 3$$

■ Usually bound X using $B = 6\sigma$

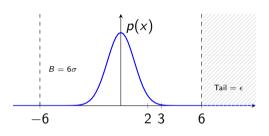
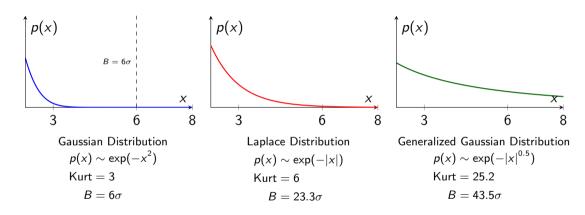


Figure: Gaussian Distribution with 6σ Bound

$$P(|X|>B)= ext{erfc}\left(rac{B}{\sigma\sqrt{2}}
ight)pprox 2^{-28}=\epsilon$$

Kurtosis and Bound



- Trend: Tail decays slower \(\sqrt{\), Tail heavier \(\sqrt{\), Kurtosis \(\sqrt{\), Bound \(\sqrt{\)} \
- Kurtosis $\gg 3$ \Rightarrow not Gaussian

Main Theorems

Let $f_i \leftarrow \mathcal{N}(0,1)$ be independent Gaussian polynomials

Theorem (∏ Indep)

$$F = \prod_{i}^{k} f_{i}$$

$$Kurt(F) = 3 + 3 \frac{2^{k} - 2}{N}$$

Theorem $(\prod Same)$

$$F = f^k$$

$$Kurt(F) = 3 + 3 \frac{\binom{2k}{k} - 2}{N}$$

Theorem (Mixed ∏)

$$F=\prod f_i^{k_i}$$

$$Kurt(F) = 3 + 3 \frac{\prod {2k_i \choose k_i} - 2}{N}$$

- \blacksquare k is multiplication depth; N is ring dimension
- For practical $N = 2^{16}$, k > 16 (or k > 10) \Rightarrow Kurt > 6 \Rightarrow F not Gaussian

Noises are not Gaussian!

in deep multiplications

Main Theorems

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Theorem (Mixed ∏)

$$F=\prod f_i^{k_i}$$

$$Kurt(F) = 3 + 3 \frac{\prod {2k_i \choose k_i} - 2}{N}$$

- Remark 1: When $N \to \infty$, Kurt $\to 3$
 - It becomes Gaussian!
 - Exactly Central Limit Theorem
 - But here *N* is *finite*, so CLT fails

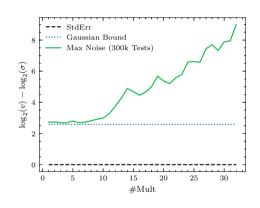
- Remark 2: When k small, Kurt ≈ 3
 - Illusion that noises are always Gaussian
 - \blacksquare Past experiments only done for small k

Remark 3: There is no widely-known name for these distributions

Experimental Results

Gaussian bound fails ⇒ Noises not Gaussian

- x-axis: mul-depth k
- Calculate the variance σ^2 thus StdErr σ
- Sample 300k times and record max noise
- Normalize to 0 to see the difference
- y-axis: max noise v.s. StdErr
 - $\log_2(v/\sigma) = \log_2(v) \log_2(\sigma)$
 - In logarithm scale!
- Gaussian bound: 6σ



$$e_1 \rightarrow e_1 e_2 \longrightarrow \cdots \longrightarrow \prod^{32} e_i$$

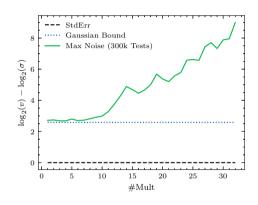
Experimental Results

Gaussian bound fails \Rightarrow Noises not Gaussian

- 8 bit overflow $\Rightarrow 256\sigma$ deviation
- If Gaussian, happens with prob 2⁻⁴⁷²⁸²
- \blacksquare When k small, noises are Gaussian-like

• Kurt =
$$3 + 3\frac{2^k - 2}{N}$$

- $k \text{ small} \Rightarrow \text{Kurt} \approx 3$
- Caused illusion that noises are Gaussian!



$$e_1 \rightarrow e_1 e_2 \longrightarrow \cdots \longrightarrow \prod^{32} e_i$$

Curve not smooth because of independent samples

Case study: How dependencies affact the variance

We also calculate the variance

Theorem $(\prod Indep)$ $Var(\prod f_i) = N^{k-1}$

$$Var(f^k) = k!N^{k-1}$$

Theorem (Mixed
$$\prod$$
)
$$Var\left(\prod f_i^{k_i}\right) = \prod k_i! N^{k-1}$$

BFV ct independent product

$$\operatorname{Var}\left(\left(\bigotimes_{i}^{k}\operatorname{ct}_{i}\right)(s) = \boxed{s^{k}} \cdot \left(\prod \mu_{\operatorname{ct}_{i}}e_{\operatorname{ct}_{j}}\right) + \cdots\right) \approx k! \cdot N^{2k-1} \cdot \operatorname{Var}(s)^{k} \cdots$$

We are able to exactly derive k! while [BMCM23] used experimental correction factor

Common dependencies \Rightarrow Variance \nearrow

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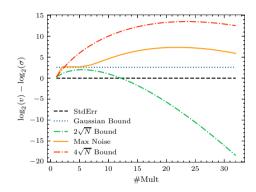
BFV ct dependent product v.s. independent product

$$\frac{\mathsf{Var}\left(\mathsf{ct}^{k}(s) = \boxed{s^{k}\mu_{\mathsf{ct}}^{k-1}} \cdot e_{\mathsf{ct}} + \cdots\right)}{\mathsf{Var}\left(\left(\bigotimes_{i}^{k}\mathsf{ct}_{i}\right)(s) = \boxed{s^{k}} \cdot \left(\prod \mu_{\mathsf{ct}_{i}}e_{\mathsf{ct}_{j}}\right) + \cdots\right)} \approx (k-1)!$$

Ciphertext dependencies ⇒ *Variance ≯*

Test the Empirical Formula in OpenFHE

- OpenFHE used $2\sqrt{N}$ empirical expansion factor
 - Originally tested using $e \cdot e'$ and $e \cdot s$
- Works for e^k , $\prod e_i$, $\prod s_i$
- Fails for s^k and modulus switching error
 - Does not affect security because of other loose factors
- Contacted OpenFHE and fixed in v1.3.1
 - Use $4\sqrt{N}$ for these special cases





Implications and Open Questions

- Software needs to track common dependencies and ciphertext dependencies
 - If they want to do average-case noise analysis
 - Means an application-specific analysis and parameter generation
 - Agrees with the Application-Aware security model [AAMP24]
 - Compiler can help here!
- What is the true distribution of the noises?
 - Noise analysis needs the bound!
 - We only calculated the kurtosis



- How can ciphertext dependencies be used for attack?
 - Recent attacks¹ [GNSJ24, CCP+24, CSBB24] exploited such dependencies in addition (+)
 - lacktriangle We are able to analyse dependencies in multiplication (imes).

¹or misconfiguration as argued in [AAMP24]

Informal Comments on CKKS Average-Case Noise Analysis

■ The major term² in CKKS noise is

$$m_1 \cdot m_2 \cdot m_3 \cdots (e_{\text{ct}})$$

- We know little about messages m_i (otherwise security implications)
- Previous works assume m_i are uniform in range [-1,1]
 - Assumption is not practical
- Need distribution analysis and range analysis depending on applications
- No good ways to do average-case
- Maybe we can only use worst-case analysis, or empirical results

²Especially for OpenFHE "reduced error" implementation

Summary

- Noises are not Gaussian after deep multiplications
- Dependencies greatly affect the variance and kurtosis of the noise
- Find flaws in empirical formula in OpenFHE

Thank you!

Questions?

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